

# MeTrApp 2011



- [Home](#)
- [Committees](#)
- [Contact](#)
- [Call for Papers and Topics](#)
- [Submission](#)
- [Deadlines](#)
- [Manuscript Guidelines](#)
- [Presentation and Publication](#)

## The First Workshop on Mechanisms, Transmissions and Applications

Timisoara, Romania  
October 06 - 08, 2011

- [Conference Site](#)
- [Registration](#)
- [Hotel Accomodation](#)
- [Travel Information](#)
- [Program](#)
- [Social Events](#)
- [Photos](#)
- [Sponsors](#)

### Presentation and Publication

The official language of the workshop is English.

All accepted papers must be orally presented.

Overhead projectors and beamers for personal computers will be available.

Each paper will be reviewed and the papers selected by the Scientific Committee will be published in a book edited by Springer.



copyright © mctr

# MECHANISMS AND MACHINE SCIENCE

Volume 3

---

*Series Editor*

MARCO CECCARELLI

For further volumes:

<http://www.springer.com/series/8779>

Erwin-Christian Lovasz · Burkhard Corves  
Editors

# Mechanisms, Transmissions and Applications

 Springer

*Editors*

Erwin-Christian Lovasz  
Politehnica University of Timișoara  
Mechanical Engineering Faculty  
Bv. Mihai Viteazul 1  
RO-300222 Timișoara  
Romania  
erwin.lovasz@mec.upt.ro

Prof. Dr. Burkhard Corves  
RWTH Aachen  
University Aachen  
Eilfschornsteinstrasse 18  
52056 Aachen  
Germany  
corves@igm.rwth-aachen.de

ISSN 2211-0984

ISBN 978-94-007-2726-7

e-ISBN 978-94-007-2727-4

DOI 10.1007/978-94-007-2727-4

Springer Dordrecht Heidelberg London New York

Library of Congress Control Number: xxxxxxxxxx

© Springer Science+Business Media B.V. 2012

No part of this work may be reproduced, stored in a retrieval system, or transmitted in any form or by any means, electronic, mechanical, photocopying, microfilming, recording or otherwise, without written permission from the Publisher, with the exception of any material supplied specifically for the purpose of being entered and executed on a computer system, for exclusive use by the purchaser of the work.

Printed on acid-free paper

Springer is part of Springer Science+Business Media ([www.springer.com](http://www.springer.com))

# Contents

## **Part I History of Mechanisms and Machine Science and Teaching Methods**

- 1 On the Evolution of Graphical Representation of Gears**  
Ceccareli M, Cigola M.
- 2 Kurt Hain and Walther Meyer zur Capellen: A View from Aachen at Two Shapers of German Mechanism Theory**  
Corves B.
- 3 thinkMOTION - DMG-Lib goes Europeana**  
U. Döring, R. Brecht, T. Brix
- 4 Multilingual Illustrated  $\mu$ -thesaurus in Mechanisms Science**  
E.-C. Lovasz, D. Perju, B. Corves, T. Brix, K.-H. Modler, I. Maniu, C.M. Gruescu, A. Lovasz and V. Ciupe
- 5 A General Classification for Mechanisms Regarding the Motion Task**  
B. Corves, S. Kurtenbach, M. Hüsing, C. Schneider

## **Part II Mechatronic and Biomechanic Applications**

- 6 Developments of a Knee Motion Assist Mechanism for Wearable Robot with a Non-circular Gear and Grooved Cams**  
H. Terada, Y. Zhu, M. Suzuki, C. Cheng, R. Takahashi
- 7 Force Distribution for a Walking Robot with Articulated Body**  
I. Doroftei, Ghe. Plesu and B. Stirbu
- 8 Numerical Root Finding from an Engineer's Point of View**  
M. Färber and U. Döring
- 9 Kinetostatic Analysis of an Articulated Walking Mechanism**  
F. Moldovan, V. Dolga and C. Pop

- 10 A Mirror Tracking Mechanism**  
N.M. Dehelean, L.M. Dehelean
- 11 Choppers: Optomechatronic Devices for the Controlled Modulation of Light**  
V.-F. Duma, M. F. Nicolov, M. Kiss, T. Ilca, C. Mnerie, D. Demian, L. Szantho
- 12 Motion Laws of a Varifocal Objective Working with a 1/2" CCD Camera**  
C.M. Gruescu

### **Part III Mechanisms and Machine Design**

- 13 A New Principle of Adaptive Compliant Gripper**  
D. Petkovic, N. D. Pavlovic
- 14 Optimum Design of Cam Mechanisms**  
I. Simionescu, M. Ene, L. Ciupitu
- 15 Linkage Solutions for the Manufacture of Complex, Thermoplastic Lightweight Structures**  
M. Krahl, U. Hanke, K.-H. Modler
- 16 RBS Simulation of Integrated Piezo-Ceramic Actuation for Textile Reinforced Composite Compliant Mechanisms**  
N. Modler, K.-H. Modler, W. Hufenbach, D. Margineanu, E.-C. Lovasz, D. Perju, E. Ianosi

### **Part IV Computational and Experimental Methods and Dynamics of Mechanisms and Machines**

- 17 Maximally Regular Planar Non Fully Parallel Manipulators**  
G. Gogu
- 18 An Experimental Characterization of a Rickshaw Prototype**  
T. Li, M. Ceccarelli
- 19 Considerations upon the Influence of Manufacturing and Assembly Errors on the Kinematic and Dynamic Behavior in a Flight Simulator Stewart-Gough Platform**  
A. Pislă, T. Itul, D. Pislă, A. Szilaghyi
- 20 Characterization of Flexure Hinges Using the Script Oriented Programming within a FEM Software Application**  
I. Ivanov, B. Corves

- 21 Basic Result on Type II DM Self-motions of Planar Stewart Gough Platforms**  
G. Nawratil
- 22 Active Bearing for Vibration Damping of Roller Systems with Piezoelectric Actuators**  
M.-C. Voicu, R. Schmidt, B. Lammen, M. Mersch, I. Maniu
- 23 On the Kinematics of a Hybrid Parallel Robot Used in Minimally Invasive Surgery**  
M. Suci, B. Gherman, C. Vaida, N. Plitea, D. Pislă

#### **Part V Mechanical Transmissions**

- 24 Synthesis of Toothed Continuously Variable Transmission (CVT)**  
K. S. Ivanov
- 25 Differential Planetary Gear Transmissions Usable in Renewable Energy Systems**  
R. Saulescu, C. Jaliu, D. Ciobanu, D. Diaconescu
- 26 Loading Devices for Closed-loop Gear Test Stands**  
C. M. Gruescu, I. Nicoara, E. Busa

#### **Author Index**

# Contributors

**R. Brecht** Ilmenau University of Technology, Ilmenau, Germany,  
r.brecht@tu-ilmenau.de

**T. Brix** Ilmenau University of Technology, Ilmenau, Germany,  
torsten.brix@tu-ilmenau.de

**E. Busa** “Politehnica” University of Timisoara, Timisoara, Romania,  
busaeugen@yahoo.com

**M. Ceccarelli** LARM: Laboratory of Robotics and Mechatronics, University  
of Cassino, Cassino, Italy, ceccarelli@unicas.it

**C. Cheng** University of Yamanashi, Yamanashi, Japan

**B. Corves** RWTH Aachen University, Aachen, Germany,  
corves@igm.rwth-aachen.de

**M. Cigola** DART, University of Cassino, Cassino Frosinone, Italy,  
cigola@unicas.it

**D. Ciobanu** Transilvania University of Brasov, Brasov, Romania,  
daniela.ciobanu@unitbv.ro

**V. Ciupe** Universitatea “Politehnica” din Timișoara, Timișoara, Romania

**L. Ciupitu** “Politehnica” University of Bucharest, Bucharest, Romania,  
liviu.ciupitu@omtr.pub.ro

**L.M. Dehelean** “Politehnica” University of Timisoara, Timisoara, Romania,  
liana.dehelean@mec.upt.ro

**N.M. Dehelean** “Politehnica” University of Timisoara, Timisoara, Romania,  
nicolae.dehelean@mec.upt.ro

**D. Demian** “Aurel Vlaicu” University of Arad, Arad, Romania

**D. Diaconescu** Transilvania University of Brasov, Brasov, Romania,  
dvdiaconescu@unitbv.ro

**A. Pisla** “Technical” University of Cluj-Napoca, Cluj-Napoca, Romania,  
adrian.pisla@muri.utcluj.ro

**D. Pisla** Technical University of Cluj-Napoca, Cluj-Napoca, Romania,  
doina.pisla@mep.utcluj.ro

**C. Pop** “Politehnica” University of Timișoara, Timișoara, Romania,  
cristian.pop@mec.upt.ro

**R. Saulescu** Transilvania University of Brasov, Brasov, Romania,  
rsaulescu@unitbv.ro

**R. Schmidt** University of Applied Sciences Osnabrück, Osnabrück, Germany,  
reinhard.schmidt@hs-osnabrueck.de

**C. Schneider** RWTH Aachen University, Aachen, Germany,  
c.schneider@igm.rwth-aachen.de

**I. Simionescu** “Politehnica” University of Bucharest, Bucharest, Romania,  
simionescu2@gmail.com

**B. Stirbu** “Gheorghe Asachi” Technical University, Iași, Romania

**M. Suciu** Technical University of Cluj-Napoca, Cluj-Napoca, Romania,  
marius.suciu@mep.utcluj.ro

**M. Suzuki** University of Yamanashi, Yamanashi, Japan

**L. Szantho** “Aurel Vlaicu” University of Arad, Arad, Romania

**A. Szilaghyi** “Technical” University of Cluj-Napoca, Cluj-Napoca, Romania

**R. Takahashi** Suncall Engineering Corporation, Japan,  
rei-takahashi@suncall-eng.co.jp

**H. Terada** University of Yamanashi, Yamanashi, Japan, terada@yamanashi.ac.jp

**C. Vaida** Technical University of Cluj-Napoca, Cluj-Napoca, Romania,  
calin.vaida@mep.utcluj.ro

**M.-C. Voicu** University “Politehnica” Timisoara, Timisoara, Romania; University  
of Applied Sciences Osnabrück, Osnabrück, Germany, c.voicu@hs-osnabrueck.de

**Y. Zhu** University of Yamanashi, Yamanashi, Japan

# Differential Planetary Gear Transmissions Usable in Renewable Energy Systems

R. Saulescu, C. Jaliu, D. Ciobanu, and D. Diaconescu

**Abstract** Many of the renewable energy systems (RES) use planetary gears for the speed increase or reduction. The paper presents a 2 DOF planetary gear transmission to be used as “speed increaser” in the counter-rotating wind turbines, hydropower plants, and, also as “speed reducer”, in the tracking systems that equip the solar photovoltaic or solar thermal systems. The transmission modelling, simulation and examples of applications in the field of renewable energy systems is presented in the paper.

**Keywords** Renewable energy system (RES) · Planetary gear · Counter-rotating

## 1 Introduction

Increased fossil fuel prices, reduced fossil fuel stocks and concern for specialists to minimize emissions of greenhouse effect gas have led to increased interest for using renewable energy sources. The main renewable energy source is the sun. The direct conversion of solar radiation into electricity can be done by using photovoltaic panels [2]. Thermal energy can be obtained from solar radiation by using solar collectors. Using the indirect conversion, solar radiation can be transformed into electricity by means of wind turbines or hydropower plants [1,9,16,17]. In case of solar collectors or photovoltaic panels, because of the sun position change on the sky, these systems use tracking mechanisms to increase the amount of solar radiation. Tracking systems are classified by their motions: rotation around one axis or around two axes; they are composed of linkages or gear mechanisms driven by linear actuators or gear-motor.

In case of wind turbines and hydropower plants, a gearbox can be used to transmit motion from rotor / turbine to generator [6,7,8,10,11,12,13]. Three basic types of gearboxes are used: belt transmissions [9], parallel-shaft gears [15,17] and 1 DOF planetary gears [1,6]. In the first two cases, the dimensions and cost increase

---

R. Saulescu (✉)  
Transilvania University of Brasov, Brasov, Romania  
e-mail: rsaulescu@unitbv.ro